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### **Control In Robotics - IEEE Control Systems Society**

Contribution Leading To New Control Theory. Several Other Methods Of Robust Control, Such As Sliding Modes And Lyapunov Methods, Have Also Been Applied To The Robust Control Problem For Robot Manipulators. The Mid-1980s Were Also A Time Of Development In Adaptive Control, And Again The Connection With Robotics Was Pursued. 1th, 2024

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Panos J Antsaklis, And Anthony N. Michel, Linear Systems, New - Age International (P) LTD. Publishers, 2009. 5. John J D'Azzo And C. H. Houpis , "Linear Control System Analysis And Design Conventional And Modern", McGraw - Hill Book Company, 1988. 6. B.N. Dutta, Numerical Methods For Linear Control Systems - , Elsevier Publication, 2007. ... 1th, 2024

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