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Control Systems In This Section We Consider The Dynamic Behavior Of Several Elementary Control Problems For Disturbance Variable And Set-point Changes. Solution Using The General Rule In (11-31), We First Reduce The Inner Loop To A Single Block As Shown In Fig. 11.13. To Solve The Servo Problem, Set $D_1 = D_2 = 0$. Because Fig. 11.13 Contains A ... 1th, 2024

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