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Www.makeblock.cc Lab Kit Ultimate Kit V1.1. Part List Beam 0824-144 Beam  
0824-160 Plate 3x6 2x 1x 2x DC Motor-25 Countersunk Screw M3x8 DC Motor-25  
Bracket 2x 6x Headless Screw M3x5 Shaft Connector-4 5x Timing Pulley 90T 2x 6x  
3x Bracket 3x3 Flange Bearing 4x8x3mm Shaft Collar 4mm 3x Threaded Shaft  
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Four Stepper Motors Step1. Connect The X Motor To The Connector Labeled X.  
Ensure The Red Cable Is Closest To The Green Screw Terminals On The RAMPS  
Board (Wire Orders From Left To Right: Red, Blue, Green And Black). Note: If You  
Don't Wiring By Color Order, The Motor Motion Will Be Incorrect. 1th, 2024.

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Hardware Overview - Robot Parts | Robot Kits | Robot Toys #define IMU\_SDA\_PIN 21 #define IMU\_SCL\_PIN 22 Using The IMU The IMU On The Shield Is The LSM9DS1, Which Is Connected The The ESP32 Thing To The I2C Port Only. Any Of The

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