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Contribution Leading To New Control Theory. Several Other Methods Of Robust Control, Such As Sliding Modes And Lyapunov Methods, Have Also Been Applied To The Robust Control Problem For Robot Manipulators. The Mid-1980s Were Also A Time Of Development In Adaptive Control, And Again The Connection With Robotics Was Pursued. Jun 1th, 2024

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Vision And Robotics Uses All Areas Of AI: • Problem Solving, Planning, Search, Inference, Knowledge Representation, Learning Etc... • But We Can't Just Plug Sensors And Effectors Onto An AI Simulation And Expect It To Work • Have Constraints Such As: • Limited, Noisy, Raw Information • Continuous Dynamic P Jun 6th, 2024

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