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Tracking & SLAM Minimally Invasive Surgery Tracking Using Detect And Match Approach We Want To Track Features For Long Periods Of Time, Redetection After Occlusion, Robust To Changes In Lighting, Rotation, Scale And Deformation. Many Different Approaches To Tracking (detect And Match) SIFT/SURF/colour Invariant. Which Work Well? Can We Combine Approaches To Exploit Their Individual ... Jan 23th, 2024.

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